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## D(M)S-180 Series — 177 lb-in (20 Nm) Electric Actuator

## **IOM Manual**



# **Table of Contents**

D(M)S-180 Series - Installation, Operation and Maintenance Manual

Technical Specifications	2
Safety Instructions	3
Installation/Mounting Positions	4,5
Wiring	. 6-9
Dimensions	10

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DS24-180-(A)  Spring Return On/Off Opt. Auxiliary Switches (-A)  AC 24 V (19.2 to 30 V) at 50/60 Hz: Class 2, 24.6 VA running, 7.7 VA holding position; DC 24 V (21.6 to 26.4 V): Class 2, 17.6 W running, 2.8 W holding position  N/A  25 VA per Actuator	24 VAC (19.2 to 30 V) at 50/60 Hz 24 VDC (21.6 to 26.4 V)  AC 24 V (19.2 to 30 V) at 50/6 7.7 VA hold DC 24 V (21.6 to 26.4 V): Class 2, 6.  AC 19.2 to 30 V at 50/60 Hz or DC 24 V ±10%, Class 2; Switch selectable direct or reverse action with signal increase  20 VA pe	DMS24-180-(A)  Spring Return Modulating Opt. Auxiliary Switches (-A)  1. (20 Nm)  (60 Hz: Class 2, 15.5 VA running, ding position; TW Running, 2.9 W holding position  Factory Set DC 0 to 10 V, CW Rotation with signal increase; Selectable DC 0 (2) to 10 V or 0 (4) to 20 mA with field furnished 500 Ohm, 0.25 W minimum resistor; switch selectable direct or reverse action with signal increase  Actuator  Voltage Input: 100,000 Ohms; Current Input: 500 Ohms with field furnished 500 ohm resistor 0 (2) to 10 VDC for desired rotation range up to 90°; Corresponds to rotation limits, 1 mA maximum	DS120-180-(A)  Spring Return On/Off Opt. Auxiliary Switches (-A)  AC 120 V (102 to 132 V) at 60 Hz  AC 120 V (AC 102 to 132 V) at 60 Hz 0.25 A running, 0.13 A holding position  N/A  N/A  N/A  N/A			
On/Off Opt. Auxiliary Switches (-A)  AC 24 V (19.2 to 30 V) at 50/60 Hz: Class 2, 24.6 VA running, 7.7 VA holding position; DC 24 V (21.6 to 26.4 V): Class 2, 17.6 W running, 2.8 W holding position  N/A  25 VA per Actuator	On/Off & Floating Opt. Auxiliary Switches (-A)  177 lb-in 24 VAC (19.2 to 30 V) at 50/60 Hz 24 VDC (21.6 to 26.4 V)  AC 24 V (19.2 to 30 V) at 50/6  T.7 VA hold DC 24 V (21.6 to 26.4 V): Class 2, 6.  AC 19.2 to 30 V at 50/60 Hz or DC 24 V ±10%, Class 2; Switch selectable direct or reverse action with signal increase  20 VA pe	Modulating Opt. Auxiliary Switches (-A)  n. (20 Nm)  GO Hz: Class 2, 15.5 VA running, ding position; TW Running, 2.9 W holding position  Factory Set DC 0 to 10 V, CW Rotation with signal increase; Selectable DC 0 (2) to 10 V or 0 (4) to 20 mA with field furnished 500 Ohm, 0.25 W minimum resistor; switch selectable direct or reverse action with signal increase  Pr Actuator  Voltage Input: 100,000 Ohms; Current Input: 500 Ohms with field furnished 500 ohm resistor  0 (2) to 10 VDC for desired rotation range up to 90°; Corresponds to rotation limits, 1 mA maximum	AC 120 V (102 to 132 V) at 60 Hz  AC 120 V (AC 102 to 132 V) at 60 Hz  AC 120 V (AC 102 to 132 V) at 60 Hz  0.25 A running, 0.13 A holding position  N/A  N/A			
AC 24 V (19.2 to 30 V) at 50/60 Hz: Class 2, 24.6 VA running, 7.7 VA holding position; DC 24 V (21.6 to 26.4 V): Class 2, 17.6 W running, 2.8 W holding position  N/A  25 VA per Actuator	177 lb-in 24 VAC (19.2 to 30 V) at 50/60 Hz 24 VDC (21.6 to 26.4 V)  AC 24 V (19.2 to 30 V) at 50/6 7.7 VA hold DC 24 V (21.6 to 26.4 V): Class 2, 6:  AC 19.2 to 30 V at 50/60 Hz or DC 24 V ±10%, Class 2; Switch selectable direct or reverse action with signal increase  20 VA pe	h. (20 Nm)  60 Hz: Class 2, 15.5 VA running, ding position;  7 W Running, 2.9 W holding position  Factory Set DC 0 to 10 V, CW Rotation with signal increase; Selectable DC 0 (2) to 10 V or 0 (4) to 20 mA with field furnished 500 Ohm, 0.25 W minimum resistor; switch selectable direct or reverse action with signal increase  Property of the control of	AC 120 V (102 to 132 V) at 60 Hz  AC 120 V (AC 102 to 132 V) at 60 Hz 0.25 A running, 0.13 A holding position  N/A  N/A			
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25 VA per Actuator	24 V ±10%, Class 2; Switch selectable direct or reverse action with signal increase  20 VA pe	Rotation with signal increase; Selectable DC 0 (2) to 10 V or 0 (4) to 20 mA with field furnished 500 Ohm, 0.25 W minimum resistor; switch selectable direct or reverse action with signal increase  Property Actuator  Voltage Input: 100,000 Ohms; Current Input: 500 Ohms with field furnished 500 ohm resistor  0 (2) to 10 VDC for desired rotation range up to 90°; Corresponds to rotation limits, 1 mA maximum	N/A N/A			
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	A Two Single-Pole, Do	Current Input: 500 Ohms with field furnished 500 ohm resistor 0 (2) to 10 VDC for desired rotation range up to 90°; Corresponds to rotation limits, 1 mA maximum	·			
N/.	Two Single-Pole, Do	range up to 90°; Corresponds to rotation limits, 1 mA maximum	N/A			
	_ JabioJaideed JWiterie.					
	AC 24 V, 50 VA Pilot Duty	S Will Gold Flash Gollidotti.	AC 120 V, 5.8 A Resistive, 1/4 hp, 275 VA Pilot Duty			
	Class 2	N/A				
25 VA Minimum per Actuator		25 VA Minimum per Actuator				
	48 in. (1.2 m) Halogen-Free Cable v	with 18 AWG (0.75 mm2) Wire Leads				
Integral Connectors for 3/8 in. Flexible Metal Conduit						
Manual override crank						
	Direction is Selectable with Mounting Position of Actuator Side A - Actuator Face Away for CCW Spring Return Side B - Actuator Face Away for CW Spring Return					
Power On (Running) 24 to 57 Sec. for 0 to 177 lb-in (0 to 20 N·m) at All Operating Conditions; 35 Sec. Nominal at Full Rated Load		Power On (Running) 150 Sec. for 0 to 177 lb·in (0 to 20 N·m) at All				
of Rotation for 90° of Returning) It to 1s Sec. for 0 to 177 lb-in (0 to 20 N-m) at Room Temperature; 35 Sec. Maximum for 0 to 177 lb-in (0 to 20 N-m) at -22°F (-30°C) 130 Seconds Maximum for 0 to 177			Power Off (Returning) 11 to 15 Sec. for 0 to 177 lb-in (0 to 20 N·m) at Room Temperature; 35 Sec. Maximum for 0 to 177 lb-in (to 20 N·m) at -22°F (-30°C) 130 Sec. Maximum for 0 to 177 lb-in (0 to 20 N·m) at -40°F (-40°C)			
	Protects from overload	d at all angles of rotation				
	<b>Operating</b> — 40 to 131°F (-40 to 55°C	C); 90% RH Maximum, Noncondensing				
(1 m) <b>Holding</b> < 18 dBA at 39-13/32 in. (1 m) <b>Returning</b> < 66 dBA at 39-13/32 in.	Holding < 20 dBA	(1 m) Holding < 18 dBA at 39-13/32 in. (1 m) Returning < 66 dBA at 39-13/32 in. (1 m)				
(i m)						
UL Listed, CCN X an CE Mark - John	CN XAPX, File E27734; to UL 60730-1, and UL 60730-2-14 Part 2, Particular APX7, File E27734; to CAN/CSA E607 d CAN/CSA E60730-2-14 Part 2, Parti son Controls, Inc. declares that this pr and other relevant provisions of the EN	r Requirements for Electric Actuators. 730-1, Automatic Controls for Household icular Requirements for Electric Actuato roduct is in compliance with the essentie MC Directive and Low Voltage Directive.	l and Similar Use: ors al requirements			
	Power On (Running) 24 to 57 Sec. for 0 to 177 lb-in (0 to 20 N-m) at All Operating Conditions; 35 Sec. Nominal at Full Rated Load  Power Off (Returning) 11 to 15 Sec. for 0 to 177 lb-in (0 to 20 N-m) at Room Temperature; 35 Sec. Maximum for 0 to 177 lb-in (0 to 20 N-m) at -22°F (-30°C) 130 Seconds Maximum for 0 to 177 lb-in (0 to 20 N-m) at -40°F (-40°C)  Running < 66 dBA at 39-13/32 in. (1 m)  Holding < 18 dBA at 39-13/32 in. (1 m)  Returning < 66 dBA at 39-13/32 in. (1 m)  UL Listed, CON X	25 VA Minimum	25 VA Minimum per Actuator  48 in. (1.2 m) Halogen-Free Cable with 18 AWG (0.75 mm2) Wire Leads  Integral Connectors for 3/8 in. Flexible Metal Conduit  Manual override crank  Direction is Selectable with Mounting Position of Actuator Side A - Actuator Face Away for CCW Spring Return  Adjustable from 30 to 90° CW or CCW With Optional Adjustable from 30 to 90° CW or CCW with Optional Adjustable Stop Kit; Mechanically Limited to 90°  Power On (Running) 24 to 57 Sec. for 0 to 177 lb-in (0 to 20 N-m) at All Operating Conditions; 35 Sec. Monimal at Full Rated Load  Power Off (Returning) 11 to 15 Sec. for 0 to 177 lb-in (0 to 20 N-m) at Room Temperature; 35 Sec. Maximum for 0 to 177 lb-in (0 to 20 N-m) at -22°F (-30°C) 130 Seconds Maximum for 0 to 177 lb-in (0 to 20 N-m) at -40°F (-40°C)  Protects from overload at all angles of rotation  60,000 Full stroke cycles (1,500,000 repositions)  Round Shafts - 1/2 to 3/4 in. or 12 to 19 mm Square Shafts - 3/8 and 1/2 in. or 10, 12, and 14 mm  Operating — 40 to 131°F (-40 to 55°C); 95% RH Maximum, Noncondensing Storage — -85 to 185°F (-65 to 85°C); 95% RH Maximum, Noncondensing  Running < 66 dBA at 39-13/32 in. (1 m) Holding < 18 dBA at 39-13/32 in. (1 m) Returning < 66 dBA at 39-13/32 in. (1 m) Returning < 55 dBA at 39-13/32 in. (1 m) Returning < 55 dBA at 39-13/32 in. (1 m)			

Warning - These actuators are designed for use only in conjunction with operating controls. Where an operating control failure would result in personal injury and/or loss of property, it is the responsibility of the installer to add safety devices or alarm systems that protect against, and/or warn of, control failure.

To avoid excessive wear or drive time on the motor, use a controller and/or software that provides a time-out function to remove the signal at the end of rotation (stall).

Disclaimer - The performance specifications are nominal and conform to acceptable industry standards. For application at conditions beyond these specifications, consult the nearest Bray office. Bray controls shall not be liable for damages resulting from misapplication or misuse of its products.

## **Applications**

The D(M)S24-180 Series Electric Actuators are direct-mount, spring return electric actuators that operate on AC/DC 24V power. These bidirectional actuators do not require a damper linkage, and are easily installed on dampers with 1/2 to 3/4 in. or 12 to 19 mm round shafts, or 3/8 and 1/2 in. or 10, 12, and 14 mm square shafts using the standard shaft clamp included with the actuator. An optional M9220-600 Jackshaft Coupler Kit is available for 3/4 to 1-1/16 in. or 19 to 27 mm round shafts, or 5/8 and 3/4 in. or 16, 18, and 19 mm square shafts.

A single D(M)S24-180 Series Electric Spring Return Actuator provides a running and spring return torque of 177 lb·in (20 N·m). Two or three like models mounted in tandem deliver twice or triple the torque (354 lb·in [40 N·m] or 531 lb·in [60 N·m]). Integral line voltage auxiliary switches are available on the -A models to indicate end-stop position or to perform switching functions within the selected rotation range.

#### **IMPORTANT:**

Use the D(M)S24-180 Series Electric Spring Return Valve Actuator only to control equipment under normal operating conditions. Where failure or malfunction of the electric actuator could lead to personal injury or property damage to the controlled equipment or other property, additional precautions must be designed into the control system. Incorporate and maintain other devices, such as supervisory or alarm systems or safety or limit controls, intended to warn of or protect against failure or malfunction of the electric actuator.

## Parts Included

- One D(M)S24-180 actuator with coupler
- Anti-rotation bracket
- Manual override crank
- Two M3 x 9.5 mm self-drilling sheet metal mounting screws
- Two No. 10-32 x 9/16 in. thread-forming conduit screws

## **Special Tools Needed**

- Torque wrench with 3/8 in. (10 mm) socket
- Digital voltmeter
- Fat blade screwdriver

#### Installation

The D(M)S24-180 Series Electric Spring Return Actuators mount directly to the surface in any convenient orientation using two M3 x 9.5 mm self-drilling sheet metal screws and the anti-rotation bracket (parts included with the actuator). No additional linkages or couplers are required. Electrical connections are color-coded and identified with numbers permanently marked on the actuator cable. A tag on the actuator cable identifies the electrical connections, and wiring details are also included on the actuator housing.

### **IMPORTANT:**

Do not install or use this D(M)S24-180 Series Electric Spring Return Actuator in or near environments where corrosive substances or vapors could be present. Exposure of the electric actuator to corrosive environments may damage the internal components of the device, and will void the warranty.

## Mounting

The D(M)S24-180 Series Electric Spring Return Actuators can be easily installed on dampers with 1/2 to 3/4 in. or 12 to 19 mm round shafts, or 3/8 and 1/2 in. or 10, 12, and 14 mm square shafts. An M9220-600 Jackshaft Coupler Kit is available for 3/4 to 1-1/16 in. or 19 to 27 mm round shafts, or 5/8 and 3/4 in. or 16, 18, and 19 mm square shafts; see Table 1 for more details.

If the damper shaft extends less than 3-19/32 in. (91 mm), see the Removable Coupler section for further instructions. If the damper shaft extends less than 1-5/32 in. (29 mm), install an extension recommended by the damper manufacturer.

#### Accessories

Table 1: Accessories and Replacement Parts (Order Separately)

Code Number	Description
DMPR-KC003 <sup>1</sup>	7 in. (178 mm) Blade Pin Extension (without Bracket) for Direct-Mount Damper Applications
M9000-153	Crank arm
M9000-158	Tandem Mounting Kit used to Mount Two Models of D(M)S24-180 Series Electric Spring Return Actuators
M9000-170	Remote Mounting Kit, Horizontal. Kit includes Mounting Bracket, M9000-153 Crank Arm, Ball Joint, and Mounting Bolts
M9000-171	Remote Mounting Kit, Vertical. Kit includes Mounting Bracket, M9000-153 Crank Arm, Ball Joint, and Mounting Bolts
M9000-604	Replacement Anti-rotation Bracket Kit (with Screws) for DMS24-180 Series Modluating Electric Spring Return Actuators
M9220-600	1 in. (25 mm) Jackshaft Coupler Kit (with Locking Clip) for Mounting D(M)S24-180 Series Electric Spring Return Actuators on Dampers with 3/4 to 1-1/16 in. or 19 to 27 mm Round Shafts, or 5/8 and 3/4 in. or 16,18, and 19 mm Square Shafts
M9220-601	Replacement Coupler Kit (with Locking Clip) for Mounting D(M)S24-180 Series Electric Spring Return Actuators on Dampers with 1/2 to 3/4 in. or 12 to 19 mm Round Shafts, or 3/8 and 1/2 in. or 10, 12, and 14 mm Square Shafts
M9220-602	Replacement Locking Clips for D(M)S24-180 Series Electric Spring Return Actuators (Five per Bag)
M9220-603	Adjustable Stop Kit for D(M)S24-180 Series Electric Spring Return Actuators
M9220-604	Replacement Manual Override Cranks for the D(M)S24-180 Series Electric Spring Return Actuators (Five per Bag)
M9220-610	Replacement Shaft Gripper, 10 mm Square Shaft with Locking Clip
M9220-612	Replacement Shaft Gripper, 12 mm Square Shaft with Locking Clip
M9220-614	Replacement Shaft Gripper, 14 mm Square Shaft with Locking Clip

<sup>&</sup>lt;sup>1</sup> Furnished with the damper and may be ordered separately.

# Counterclockwise (CCW) spring return direction Clockwise (CW) powered operation

For CCW spring return direction, mount the actuator to the damper shaft so that Side A of the actuator is away from the damper as illustrated in Figure 1. With power applied, the actuator drives CW from the 0° position, and spring returns CCW.

Side A: CCW Spring Return Direction

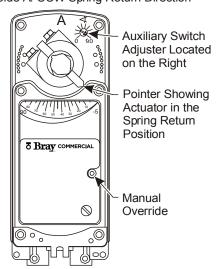


Figure 1: Side A of Actuator

## Clockwise (CW) spring return direction Counterclockwise (CCW) powered operation

To change the spring return direction to CW, mount the actuator to the damper shaft so that Side B of the actuator is away from the damper as illustrated in Figure 2. With power applied, the actuator now drives CCW from the 0° position, and spring returns CW.

Side B: CW Spring Return Direction

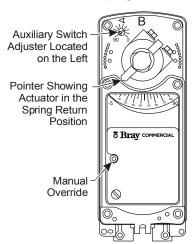


Figure 2: Side B of Actuator

## Removable Coupler

The coupler may be installed on either side of the output hub. If the damper shaft is less than 3-19/32 in. (91 mm) long, insert the coupler in the face of the actuator closest to the damper. If the damper shaft is shorter than 1-5/32 in. (29 mm) long, a shaft extension is required to mount the actuator.

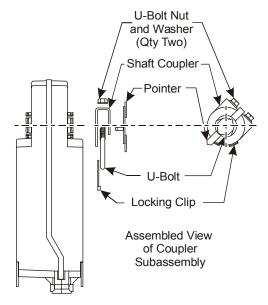


Figure 3: Changing the Position of the Coupler

# To change the position of the coupler, see Figure 3 and proceed as follows:

- 1. Mount the coupler on either Side A or Side B of the actuator, as determined by the shaft length.
- 2. Snap the locking clip securely into the coupler retention groove to retain the coupler.

#### **Manual Override**

Use only the supplied manual override crank to reposition the actuator hub when using the manual override feature.

### **IMPORTANT:**

Applying excessive torque to the manual override or running the manual override with a power tool may damage the internal components of the actuator and cause premature failure.

## To reposition the actuator hub, proceed as follows:

- 1. De-energize the actuator.
- 2. Insert the hex end of the manual override crank into the manual override adjustment point on the face of the actuator.
- 3. Rotate the manual override crank in the direction indicated by the arrow on the label.

#### NOTE:

The actuator requires 27 rotations of the manual override crank from the fully spring return position to fully reposition the actuator hub. At the end of travel, the rotational resistance increases; do not force the actuator hub past this point.

4. Rotate the manual override crank a half turn in the opposite direction to lock the actuator hub in place.

#### NOTE:

To unlock the actuator hub, rotate the manual override crank in the direction indicated by the arrow on the label. The actuator hub automatically unlocks when power is applied to the actuator, and returns the actuator to normal drive and spring return operation.

# Mounting the Actuator To mount the actuator, proceed as follows:

1. See the dimensions in Figure 4 and Table 2 to ensure the correct positioning of the anti-rotation bracket.

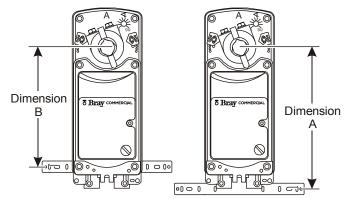


Figure 4: Positioning the anti-rotation bracket

Shaft Diameter	Dimension A, in. (mm)	Dimension A, in. (mm) 7 (178)		
1/2 to 9/16 in. (12 to 14 mm)	8-9/32 (210)			
5/8 to 3/4 in. (16 to 19 mm)	8-5/32 (207)	6-29/32 (175)		

Table 2: Dimensions from anti-rotation bracket to shaft center

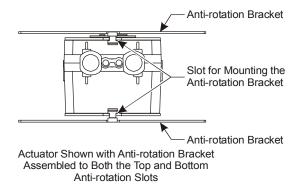
#### **IMPORTANT:**

The tab on the anti-rotation bracket must fit midpoint in the actuator slot. Positioning the tab midpoint in the slot prevents actuator binding and premature wear, and makes actuator removal easier.

2.Bend or cut the anti-rotation bracket to fit the damper frame or duct as illustrated in Figure 5.

#### NOTE:

The anti-rotation bracket can be bent to fit a round damper.



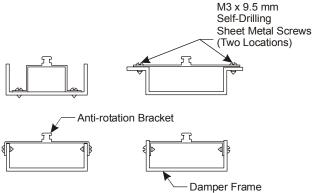


Figure 5: Fitting the anti-rotation bracket on the damper frame or duct

- 3. Drill mounting holes in the damper frame or duct using the anti-rotation bracket as a guide (based on the measurements obtained in Table 2 and Figure 4).
- 4.Secure the anti-rotation bracket to the damper frame or duct using the two M3 x 9.5 mm self-drilling sheet metal screws provided and a 1/4 in. (6 mm) blade screwdriver or 5/16 in. (8 mm) nut driver.

## **IMPORTANT:**

Do not overtighten the mounting screws to avoid stripping the threads. Be certain that the tab on the anti-rotation bracket remains properly positioned in the slot on the actuator, and that the actuator remains parallel to the mounting surface.

- 5. Slide the actuator onto the damper shaft, and position the tab of the anti-rotation bracket into the slot at the bottom of the actuator as illustrated in Figure 5.
- 6.Rotate the damper blades to the desired position if the power is lost. To ensure a tight seal, insert the manual override crank and turn it in the direction indicated by the arrow on the label five turns; the position indicator should be near the 0° position on the scale. Quickly rotate the manual override crank a half turn in the opposite direction to temporarily lock the actuator hub in place.
- 7. Evenly hand tighten each clamp nut onto the U-bolt, keeping the actuator flat. Secure the U-bolt to the damper shaft and tighten to a torque of 100 to 125 lb·in (11 to 14 N·m).
- 8. To release the spring, turn the manual override crank in the direction indicated on the label; the actuator spring returns to its starting position. If this step is omitted, the spring releases automatically when power is applied to the actuator.
- 9. Remove the manual override crank and store it in an unused mounting hole.
- 10. Apply power long enough for the actuator to travel a full stroke, and verify that the actuator rotates freely throughout the range.

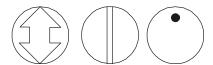
#### NOTE:

If electric power is not available, complete this verification by reinserting the manual override crank and turning it in the direction indicated to rotate the coupler to the fully open position.

## Rotation range using optional M9220-603 Adjustable Stop Kit

The actuator is factory set for 90° rotation, and its rotation range is limited in 5° increments to a minimum of 30°. Stroke limiting stops are attached in the field to the shaft coupler side of the actuator to reduce the rotation range. Attaching a stroke limiting stop in the furthest mounting position reduces the rotation range of the actuator by 5°. Each progressive mounting position reduces the rotation range an additional 5°.

1. Check that the damper blade is accessible or that its position is permanently marked on the end of the damper shaft as illustrated in Figure 6.



**Figure 6: Damper Position Icons** 

## NOTE:

Two stops are stacked on top of each other and assembled with a single screw.

2. Determine the desired rotation range. If a 65 to 90° rotation range is desired, add two stroke limiting stops stacked on each other to one side of the coupler. If a 35 to 60° rotation range is desired, add a second set of two stops stacked on each other to the other side of the coupler.

#### NOTE:

If both rotational ranges of adjustable stops are required (35° - 60° & 65° - 90°), use the manual override crank to position and lock the actuator in a mid-stroke position to gain access to both stroke limiting stop mounting positions.

3. Mount the stroke limiting stops in the desired position using the M4  $\times$  14 mm self-tapping screws provided. Tighten the screws to a torque of 35 lb-in (4 N-m).

### Example:

For a rotation range of 65°, mount two stacked stroke limiting stops in the minimum stroke position as illustrated in Figure 7.

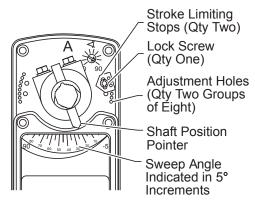


Figure 7: Stroke limiting stops mounted in the minimum stroke position for a rotation range of 65°

### **WIRING**

The DS24-180 Series On/Off Electric Spring Return Actuator provides reliable, integrated damper control. An AC 24 V at 50/60 Hz or DC 24 V input signal between the black and red wires, or an AC 120 V input signal at 60 Hz between the black and white wires, or an AC 230 V input signal at 50/60 Hz between the blue and brown wires causes the output hub to rotate from -5 to 90° (unless an external mechanical limit is reached).

Once the actuator reaches the commanded position, it holds that position until power is removed. If power is removed, the actuator spring returns to its -5° position (unless an external mechanical limit is reached). A stall condition while driving between -5 to 90° causes the output hub to stop motion and hold its position until power is removed. Rotation is mechanically limited to the -5 and 90° positions by integral end-stops. Optional end-stops are available to limit the output hub travel. An anti-rotation bracket prevents rotational movement of the actuator body.

See Figure 8 and Figure 9 for proper wiring of the DS24-180 Series On/Off Electric Spring Return Actuator.

## **CAUTION: Risk of Electric Shock.**

Disconnect the power supply before making electrical connections to avoid electric shock.

#### CAUTION: Risk of Property Damage.

Do not apply power to the system before checking all wiring connections. Short circuited or improperly connected wires may result in permanent damage to the equipment.

#### **IMPORTANT:**

Make all wiring connections in accordance with local, national, and regional regulations. Do not exceed the electrical ratings of the DS24-180 Series On/Off Electric Spring Return Actuator.

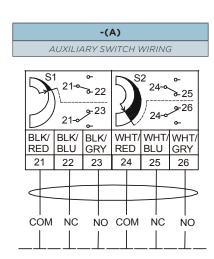
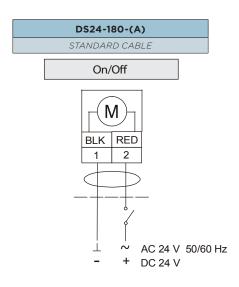


Figure 8: Auxiliary Switch Wiring for -A Models



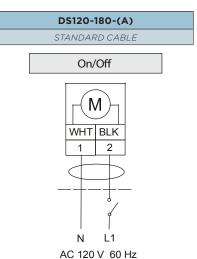


Figure 9: Control wiring diagrams

#### **WIRING**

The DS24-180-T Series On/Off & Floating Electric Spring Return Actuator provides reliable, integrated damper control. When 24 VAC at 50/60 Hz or 24 VDC power is applied between the black and red wires, and power is applied to a gray or orange control wire, the output hub rotates from -5 to 90°, based on the Reverse Acting (RA)/Direct Acting (DA) setting (unless an external mechanical limit is reached).

Once the actuator reaches the commanded position, it holds that position until power is removed. If power is removed, the actuator spring returns to its -5° position (unless an external mechanical limit is reached). A stall condition while driving between -5 to 90° causes the output hub to stop motion and hold its position until power is removed. Rotation is mechanically limited to the -5 and 90° positions by integral end-stops. Optional end-stops are available to limit the output hub travel. An anti-rotation bracket prevents rotational movement of the actuator body.

See Figure 10 and Figure 11 for proper wiring of the DS24-180 Series On/Off Electric Spring Return Actuator.

## **CAUTION: Risk of Electric Shock.**

Disconnect the power supply before making electrical connections to avoid electric shock.

#### CAUTION: Risk of Property Damage.

Do not apply power to the system before checking all wiring connections. Short circuited or improperly connected wires may result in permanent damage to the equipment.

## **IMPORTANT:**

Make all wiring connections in accordance with local, national, and regional regulations. Do not exceed the electrical ratings of the DS24-180-T Series On/Off & Floating Electric Spring Return Actuator.

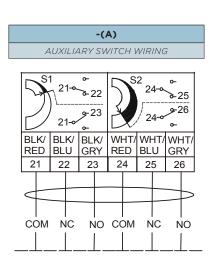
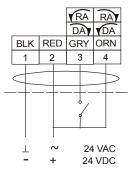


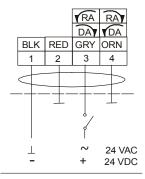
Figure 10: Auxiliary Switch Wiring for -A Models



Open/Close, Single Wire



On/Off, Two Wire



Floating Control, Four Wire

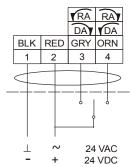


Figure 11: Control wiring diagrams

### **WIRING**

The DMS24-180 Series Modulating Electric Spring Return Actuator provides reliable, integrated damper control. An AC 24 V at 50/60 Hz or DC 24 V input signal between the black and red wires, and a DC 0(2) to 10 V input control signal, causes the output hub to rotate from -5 to 90° (unless an external mechanical limit is reached).

Once the actuator reaches the commanded position, it holds that position until power is removed. If power is removed, the actuator spring returns to its -5° position (unless an external mechanical limit is reached). A stall condition while driving between -5 to 90° causes the output hub to stop motion and hold its position until power is removed. Rotation is mechanically limited to the -5 and 90° positions by integral end-stops. Optional end-stops are available to limit the output hub travel. An anti-rotation bracket prevents rotational movement of the actuator body.

See Figure 12 and Figure 13 for proper wiring of the DMS24-180 Series Modulating Electric Spring Return Actuator.

## **CAUTION: Risk of Electric Shock.**

Disconnect the power supply before making electrical connections to avoid electric shock.

## **CAUTION: Risk of Property Damage.**

Do not apply power to the system before checking all wiring connections. Short circuited or improperly connected wires may result in permanent damage to the equipment.

## **IMPORTANT:**

Make all wiring connections in accordance with local, national, and regional regulations. Do not exceed the electrical ratings of the DMS24-180 Series Modulating Electric Spring Return Actuator.

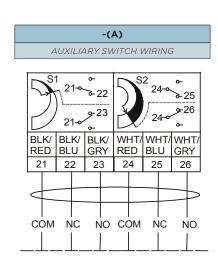


Figure 12: Auxiliary Switch Wiring for -A Models

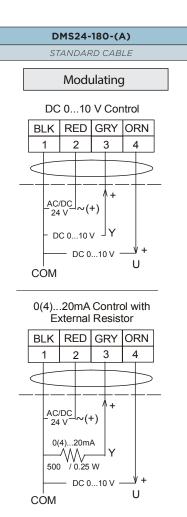


Figure 13: Control wiring diagrams

#### **WIRING**

The DS120-180 Series On/Off Electric Spring Return Actuator are direct-mount, spring return electric actuators that operate on AC 120 V (102 to 132 V) at 60 Hz. These bidirectional actuators do not require a damper linkage, and are easily installed on dampers with 1/2 to 3/4 in. or 12 to 19 mm round shafts, or 3/8 and 1/2 in. or 10, 12, and 14 mm square shafts using the standard shaft clamp included with the actuator.

Once the actuator reaches the commanded position, it holds that position until power is removed. If power is removed, the actuator spring returns to its -5° position (unless an external mechanical limit is reached). A stall condition while driving between -5 to 90° causes the output hub to stop motion and hold its position until power is removed. Rotation is mechanically limited to the -5 and 90° positions by integral end-stops. Optional end-stops are available to limit the output hub travel. An anti-rotation bracket prevents rotational movement of the actuator body.

See Figure 14 and Figure 15 for proper wiring of the DS120-180 Series On/Off Electric Spring Return Actuator.

## **CAUTION: Risk of Electric Shock.**

Disconnect the power supply before making electrical connections to avoid electric shock.

#### CAUTION: Risk of Property Damage.

Do not apply power to the system before checking all wiring connections. Short circuited or improperly connected wires may result in permanent damage to the equipment.

## **IMPORTANT:**

Make all wiring connections in accordance with local, national, and regional regulations. Do not exceed the electrical ratings of the DMS24-180 Series Modulating Electric Spring Return Actuator.

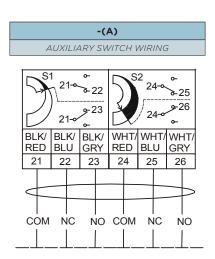


Figure 14: Auxiliary Switch Wiring for -A Models

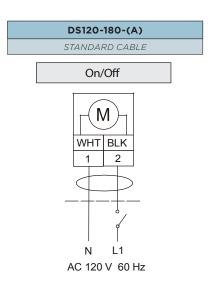


Figure 15: Control wiring diagrams

## **Setup and Adjustments**

## **Direction of Action**

The D(M)S24-180 Series Electric Spring Return Actuators are factory set for Direct Acting (DA) operation. In DA mode, applying an increasing input signal to the control input drives the actuator away from the spring return position. Reverse Acting (RA) operation is also available. In RA mode, applying an increasing input signal to the control input drives the actuator toward the spring return position. Figure 16 and Figure 17 indicate how the drive direction for the actuator depends on the spring return direction and the position of the mode selection switch.

		O consosion			
Control Inputs		Face tuator	CW Face of Actuator		
			election Setting		
	DA	RA	RA	DA	
Increasing Signal	cw	ccw	cw	ccw	
Decreasing Signal	CCW	cw	ccw	cw	

Direction Feedback		Rotation Position						
Direction	i eeuback	0°*	15°	30°	45°	60°	75°	90°
Direct	0-10V	0.0V	1.7V	3.3V	5.0V	6.7V	8.3V	10.0V
Acting	2-10V	2.0V	3.3V	4.7V	6.0V	7.3V	8.7V	10.0V
Reverse	0-10V	10.0V	8.3V	6.7V	5.0V	3.3V	1.7V	0.0V
Acting	2-10V	10.0V	8.7V	7.3V	6.0V	4.7V	3.3V	2.0V

<sup>\* 0°</sup> is the spring return position.

Figure 16: Nominal Feedback Signal Relative to Rotation Position

### Mode Selector Switch RA and DA Function

The D(M)S24-180 Series Electric Spring Return Actuators are factory set at Direct Acting (DA), DC 0 to 10 V control input (Figure 17). To change to RA operation, move the mode selection switch from DA to RA. The DC input signal is selectable from DC 0 to 10 V or from DC 2 to 10 V, which corresponds to 0 to 95° rotation. If the rotation range is reduced, the end-stop is reached with a reduced input signal.

For example, if a DC 0 to 10 V input signal is selected and the rotation range is limited to 75°, the end-stop is reached at DC 8.3 V. If an external 500 ohm resistor is placed across the input (see Figure 9), the switch positions then select between 0-20 mA or 4-20 mA.



Side A of Actuator

Side B of Actuator

Figure 17: Mode Selection

### **CAL Function**

The Calibrate (CAL) function enables the actuator to redefine the selected control input range proportionally across a reduced rotation range. The actuator stores the reduced rotation range in nonvolatile memory (retains data when power is lost or removed).

The DC 0 to 10 V input signal corresponds to -5 to 90° rotation. If the rotation range is reduced, the end-stop is reached with a reduced input signal. For example, if a DC 0 to 10 V input signal is selected and the rotation range is limited to 75°, the end-stop is reached at DC 8.3 V. After calibration, the end-stop is reached at DC 10 V.

## To calibrate the control input range, proceed as follows:

- With power off, move the mode selection switch to the CAL position (Figure 11). Then, energize the actuator. The actuator automatically rotates until the end-stops are found, and proportionally recon figures the control input range to the reduced rotation range.
- 2.Return the mode selection switch to the desired selection (example: DA, 0 to 10 VDC control input).

## NOTE:

During normal operation, if the actuator stroke increases due to seal or seat wear, the input is redefined to the increased rotation range in approximately 0.5° increments.

3. If the actuator mounting position is changed or if the linkage is adjusted, repeat Steps 1 and 2 to reinitiate the CAL function.

## NOTE:

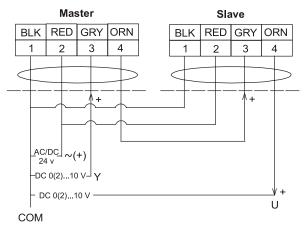
To repeat calibration with power applied, move the mode selection switch out of the CAL position for at least 2 seconds before returning it to the CAL position. Auto calibration begins 5 seconds after you return it to the CAL position.

12

## **Tandem Operation: Master with Slaves**

The tandem configuration (Figure 18 and Figure 20) provides twice (with two actuators) or triple (with three actuators) the running and spring return torque of a single actuator, or 354 lb·in (40 N·m), 531 lb·in (60 N·m). The actuators may be mounted in tandem using the M9000-158 Tandem Mounting Kit. To mount a third actuator, user-configured bracketing is required.

DC 0 (2) ...10 V Control with Tandem Connection



**Figure 18: Tandem Connection** 

## Follow these guidelines for tandem operation:

- Two or three DMS24-180 Series actuators may be operated in tandem on the same shaft. If mounting two actuators, see Figure 18; for three actuators, see Figure 20.
- 2. Each actuator requires separate 24 volt power. When two or more actuators connected in tandem share a common power source, the total maximum power draw is actually 1.5 times the normal running current for each actuator. (Total Power = Number of Actuators x Running Power x 1.5).
- 3.Only one of the actuators can be configured as the master. Set the selector switch to the master position (Figure 19).

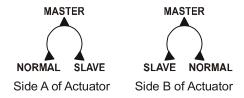


Figure 19: Tandem Selector Switch

## Follow these guidelines for tandem operation:

- 4. The other modulating actuator(s) must be configured as slave(s), by setting the tandem selector switch to the slave position.
- 5. The master can accept DC 0-10 V or DC 2-10 V, or 4-20 mA command signals based on the master's switch settings and/or external resistor.
- 6. The master and slave(s) must have matching RA/DA settings..

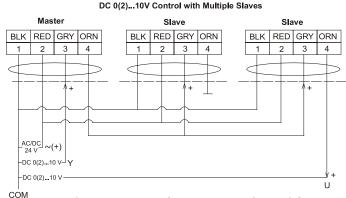


Figure 20: Tandem Connection with Three Actuators

- 7. The master and slave(s) must spring return in the same direction.
- 8. Once tandem-operating actuators are mounted to a damper shaft, manual override is no longer an available function.

The feedback wire of the master (orange) is connected to the command wire(s) of the slave(s)(gray). As the master moves response to position commands, the master sets its feedback wire to 0 volts if moving counterclockwise, 5 volts if holding, or 10 volts if moving clockwise.

Each slave actuator must have its tandem selector switch (Figure 19) set on the slave setting. Its gray command wire must be connected the master's orange feedback wire.

Position information, 0-10 (or 2-10) volts, is available on the slave actuator's feedback wire (orange).

#### NOTE:

Electrical override still functions after the actuators configured for tandem operation are mounted to a damper shaft. The actuator has a 150-second drive time when operating in this mode.

## Auxiliary Switches ((-A) Model Only)

The (-A) models include two integral auxiliary switches with a switch adjuster accessible on either face of the actuator (as illustrated in Figure 1 and Figure 2). The nominal factory setting for Auxiliary Switch No. 1 is 11° closing, and the nominal factory setting for Auxiliary Switch No. 2 is 81° opening (relative to a 0 to 90° rotation range).

See the Technical Specifications table for the auxiliary switch ratings.

## WARNING: Risk of Electric Shock.

Disconnect or isolate all power supplies before making electrical connections. More than one disconnect or isolation may be required to completely de-energize equipment. Contact with components carrying hazardous voltage can cause electric shock and may result

The switch point of Auxiliary Switch No. 1 is fixed. The switch point of Auxiliary Switch No. 2 is independently and continuously adjustable from 25 to 95°. See Figure 21 and use the method in the following example for the most accurate positioning of Auxiliary Switch No. 2.

# To change the switch point of Auxiliary Switch No. 2, proceed as follows:

1. Position the actuator in the full spring return position.

#### NOTE:

Auxiliary Switch No. 2 is factory set to trip when the actuator reaches the 81° position.

2. Rotate the switch adjuster until it points to the desired switch point.

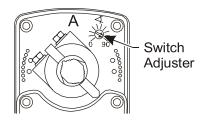


Figure 21: Switch Point Settings

- 3. Connect Auxiliary Switch No. 2 to a power source or an ohmmeter, and apply power to the actuator. The actuator moves to the fully open position and holds while power is applied.
- 4. Observe the switch point. If required, repeat Steps 2 and 3.

## **Repairs and Replacement**

A number of replacement parts are available; see Table 1 for more details. If the D(M)S24-180 Electric Spring Return Actuator fails to operate within its specifications, replace the unit.

## **Setup and Adjustments**

### **Direction of Action**

The DS24-180-T On/Off Floating Electric Spring Return Actuators are factory set for Direct Acting (DA) operation but may also be switched to Reverse Acting (RA) operation. A control input drives the actuator.

Figure 22 and Figure 23 indicate how the drive direction for the actuator depends on the spring return direction and the position of the mode selection switch.

Control Inputs			000000	B	
			Face tuator	CW Face of Actuator	
				election Setting	
GRY 3	ORN 4	DA	RA	RA	DA
CLOSED	OPEN	CW	ccw	CW	CCW
OPEN	CLOSED	ccw	cw	ccw	CW
OPEN	OPEN	Holds Position			
CLOSED	CLOSED	cw ccw cw c			CCW

Figure 22: Settings for Drive Direction

#### Mode Selector Switch RA and DA Function

The DS24-180-T Floating Electric Spring Return Actuators are factory set at DA, 90 degrees of travel as illustrated in Figure 23. To reverse the rotation, either move the mode selection switch from Direct Acting (DA) to Reverse Acting (RA), or reverse the control input wiring to GRY 3 and ORN 4.



Figure 23: Mode Selection

## **Tandem Operation**

The tandem configuration provides twice the running and spring return torque of a single actuator (354 lb·in [40 N·m]). Two similar actuators can be mounted in tandem using the Tandem Mounting Kit operate together.

Use two or three actuators from the same model type for tandem operation. Actuators used in the tandem configuration are wired in parallel (as illustrated in Figure 24).

#### NOTE:

Manual override does not function after the actuators configured for tandem operation are mounted to a damper shaft.

Floating Control, Four Wire with Tandem Connection

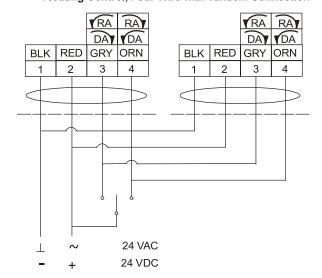


Figure 24: Tandem Connection

## Auxiliary Switches ((-A) Models Only)

The -A models include two integral auxiliary switches with a switch adjuster accessible on either face of the actuator (as illustrated in Figure 1 and Figure 2). The nominal factory setting for Auxiliary Switch No. 1 is 11° closing, and the nominal factory setting for Auxiliary Switch No. 2 is 81° opening (relative to a 0 to 90° rotation range).

See the Technical Specifications table for the auxiliary switch ratings.

#### WARNING: Risk of Electric Shock.

Disconnect or isolate all power supplies before making electrical connections. More than one disconnect or isolation may be required to completely de-energize equipment. Contact with components carrying hazardous voltage can cause electric shock and may result

The switch point of Auxiliary Switch No. 1 is fixed. The switch point of Auxiliary Switch No. 2 is independently and continuously adjustable from 25 to 95°. See Figure 25 and use the method in the following example for the most accurate positioning of Auxiliary Switch No. 2.

To change the switch point of Auxiliary Switch No. 2, proceed as follows:

1. Position the actuator in the full spring return position.

## NOTE:

Auxiliary Switch No. 2 is factory set to trip when the actuator reaches the 81° position.

2. Rotate the switch adjuster until it points to the desired switch point.

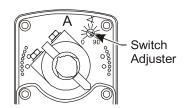


Figure 25: Switch Point Settings

- 3. Connect Auxiliary Switch No. 2 to a power source or an ohmmeter, and apply power to the actuator. The actuator moves to the fully open position and holds while power is applied.
- 4. Observe the switch point. I f required, repeat Steps 2 and 3.

## **Dimensions**

